

# A quick note on advection of localization

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/home/ross/DataAssim/Notes/AdvectionLocalization.lyx

Without advection the 4D Schur product is

$$\underline{\mathbf{P}} \circ \underline{\mathbf{L}} = \begin{pmatrix} \mathbf{P}_{11} & \mathbf{P}_{12} & \cdots & \mathbf{P}_{1L} \\ \mathbf{P}_{21} & \mathbf{P}_{22} & & \\ \vdots & & & \\ \mathbf{P}_{L1} & & & \mathbf{P}_{LL} \end{pmatrix} \circ \begin{pmatrix} \mathbf{L} & \mathbf{L} & \cdots & \mathbf{L} \\ \mathbf{L} & \mathbf{L} & & \\ \vdots & & & \\ \mathbf{L} & & & \mathbf{L} \end{pmatrix},$$

where  $\mathbf{P}_{ij}$  is the ensemble's 3D sample error covariance matrix between time steps  $i$  and  $j$ ,  $\mathbf{L}$  is the 3D localization correlation matrix, and the underlines indicate a 4D operator. Note that

$$\begin{pmatrix} \mathbf{L} & \mathbf{L} & \cdots & \mathbf{L} \\ \mathbf{L} & \mathbf{L} & & \\ \vdots & & & \\ \mathbf{L} & & & \mathbf{L} \end{pmatrix} = \begin{pmatrix} \mathbf{I} \\ \mathbf{I} \\ \vdots \\ \mathbf{I} \end{pmatrix} \mathbf{L} \begin{pmatrix} \mathbf{I} & \mathbf{I} & \cdots & \mathbf{I} \end{pmatrix} = \begin{pmatrix} \mathbf{L}^{1/2} \\ \mathbf{L}^{1/2} \\ \vdots \\ \mathbf{L}^{1/2} \end{pmatrix} \begin{pmatrix} \mathbf{L}^{T/2} & \mathbf{L}^{T/2} & \cdots & \mathbf{L}^{T/2} \end{pmatrix}.$$

The square-root of this is

$$\underline{\mathbf{L}}^{1/2} = \begin{pmatrix} \mathbf{L}^{1/2} \\ \mathbf{L}^{1/2} \\ \vdots \\ \mathbf{L}^{1/2} \end{pmatrix}.$$

Recall that the square-root of the localization matrix can be interpreted as a matrix of quasi ensemble members whose covariance is the localization. This allows us to introduce advection into the problem by simply replacing the above with

$$\underline{\mathbf{L}}^{1/2} = \begin{pmatrix} \mathbf{L}^{1/2} \\ \mathbf{M}\mathbf{L}^{1/2} \\ \vdots \\ \mathbf{M}^{T-1}\mathbf{L}^{1/2} \end{pmatrix},$$

where  $\mathbf{M}$  is the advection operator (for one time step).